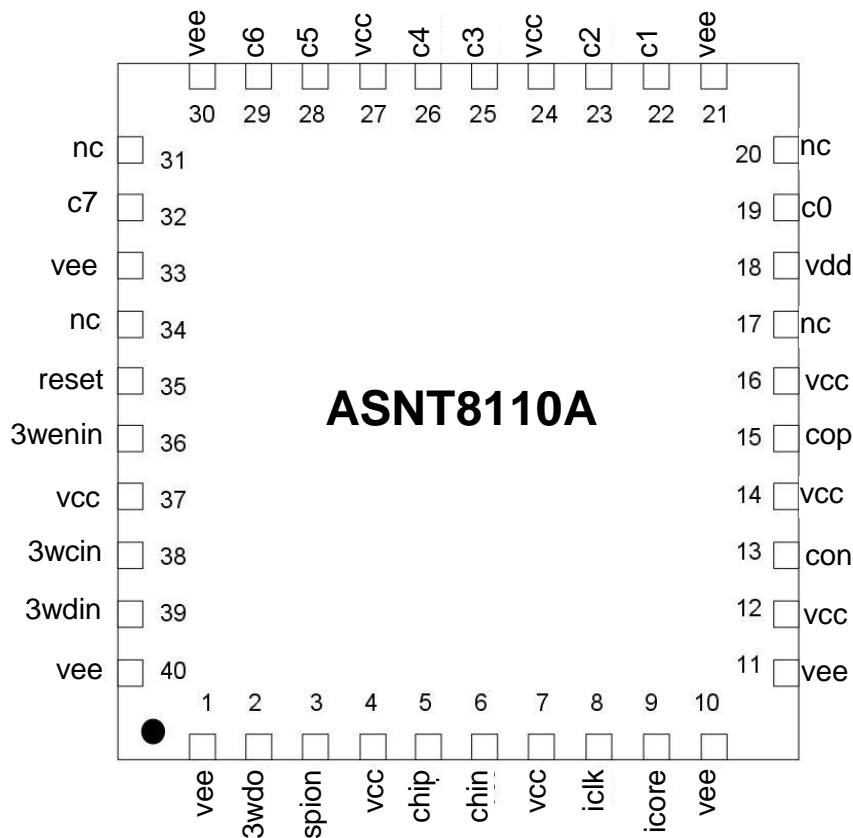




ASNT8110A-PQB DC-to-24GHz Programmable Integer Divider with SPI

- Wide frequency range from DC to 24GHz
- Continuous division ratios from 1 to 256
- 50% duty cycle of the output divided clock signal
- Fully differential CML input and output interfaces
- Adjustable power consumption
- Easy 8-bit parallel programming interface compatible with CMOS/LVTTL standards
- Optional external reset function
- Dynamic division ratio adjustment with a short set-up time (about 20ns after the pulse edge on any control input)
- Single +2.8V or -2.8V power supply
- Industrial temperature range
- Standard 40-pin QFN package with a thermal pad



DESCRIPTION

ASNT8110A-PQB is a high-speed programmable integer clock divider with dynamic adjustment of the division ratio. An optional external active-high CMOS/LVTTL reset signal is also provided. The functional block diagram of the device is shown in Fig. 1.

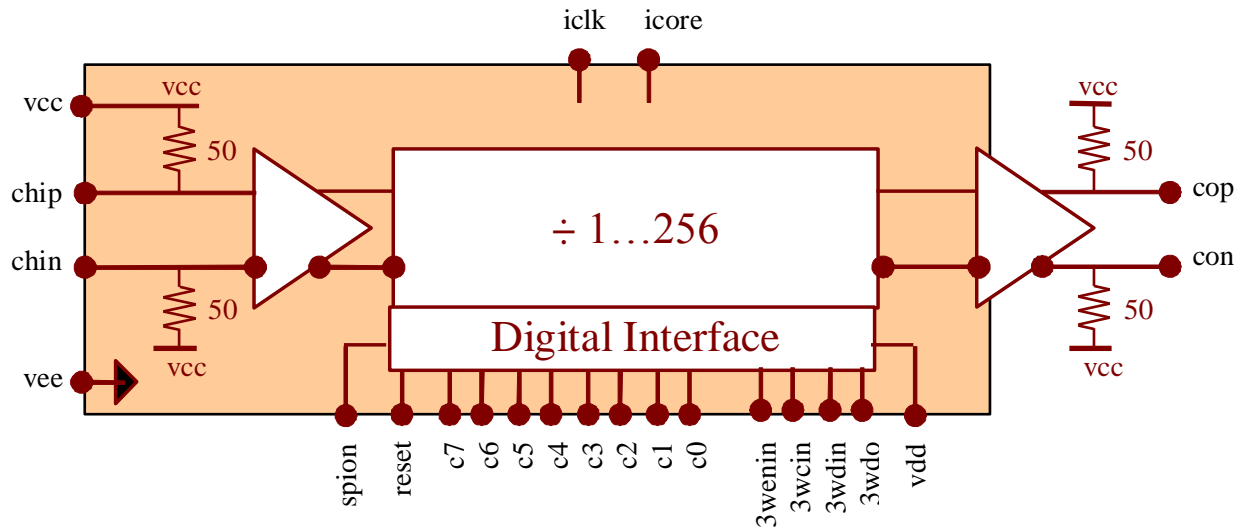


Fig. 1. Functional Block Diagram

The divider accepts an input clock signal (**chip/chin**) with a speed from DC to the maximum specified frequency and provides a clean 50% duty cycle output divided clock signal (**cop/con**) in any operational mode. The divider allows for dynamic adjustment of the division ratio from 1 to 256 with a step of 1 through either full-scale CMOS 8-bit parallel interface or 1.2V CMOS 3-wire SPI. The parallel or serial interface mode is selected with a full-scale CMOS control signal **spion**.

In the parallel mode, a binary code on the control inputs (**c0-c7**) defines the value of the ratio from 1 to 255, where **c7** is the most significant bit (MSB). All “0”s (“low” state) define the division by 256. Following any change of any control signal, the divider switches to idle after (64...128) periods of the high-speed system clock plus an additional 1.6ns delay, and returns back to normal operation with the new division ratio after an additional delay equal to 192 periods of the high-speed system clock.

In the serial mode, the 1-byte division coefficient code is supplied through the 3-wire interface with MSB first as shown in Fig. 2. Input data **3wdin** are sampled at rising edges of SPI clock **3wcin** and internal division coefficient value will be updated at a rising edge of the **3wenin** signal.

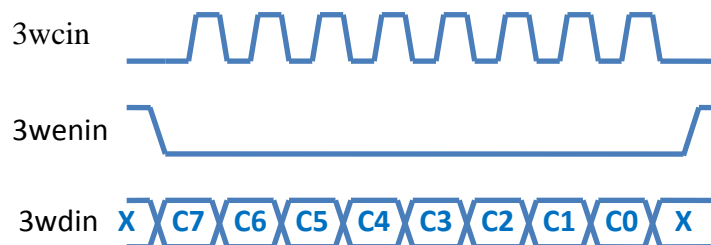


Fig. 2. SPI Bit Order



The device automatically resets itself after the initial power-up and any change of the division control signals. When the optional external reset signal **reset** is set to “high”, the divider switches to idle (static “0” output) after a $0.7ns$ delay as shown in the timing diagram in Fig. 3. When **reset** returns to “low”, the divider switches back to normal operation after $(64..128)$ periods of the high-speed system clock plus an additional $1.6ns$ of delay. The minimum allowed **reset** pulse must be longer than 64 periods of the high-speed system clock.

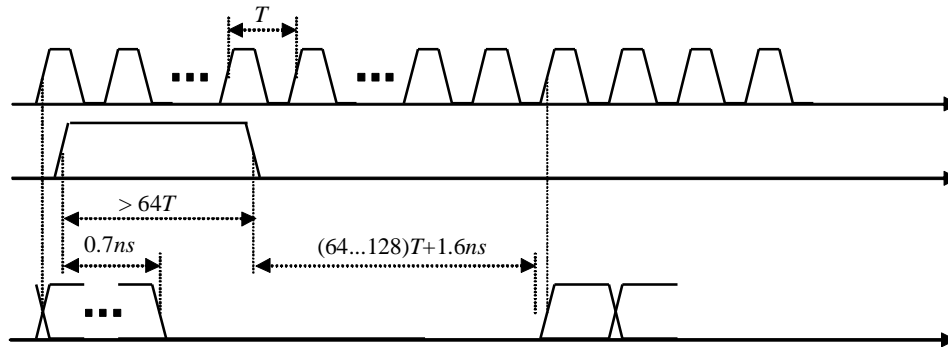


Fig. 3. Timing Diagram

The part's I/O's support the CML logic interface with on chip 50Ω termination to **vcc** and may be used differentially, AC/DC coupled, single-ended, or in any combination (also see POWER SUPPLY CONFIGURATION). In the DC-coupling mode, the input signal's common mode voltage should comply with the specifications shown in ELECTRICAL CHARACTERISTICS. In the AC-coupling mode, the input termination provides the required common mode voltage automatically. The differential DC signaling mode is recommended for optimal performance.

POWER SUPPLY CONFIGURATION

The part can operate with either a negative supply ($v_{cc}=0.0V=\text{ground}$), or a positive supply ($v_{ee} = 0.0V = \text{ground}$). In case of the positive supply, all I/Os need AC termination when connected to any devices with 50Ω termination to ground. Different PCB layouts will be needed for each different power supply combination.

The parts power consumption may be reduce by up to 30% using external resistors to connect the control ports **iclk** and **icore** to **v_{ee}**. **It is recommended to activate iclk first and then activate icore if required because current reduction results in a lower maximum operational frequency and icore has larger impact than iclk!**

All the characteristics detailed below assume $v_{cc} = +2.8V$ and $v_{ee} = 0V$.

ABSOLUTE MAXIMUM RATINGS

Caution: Exceeding the absolute maximum ratings shown in Table 1 may cause damage to this product and/or lead to reduced reliability. Functional performance is specified over the recommended operating conditions for power supply and temperature only. AC and DC device characteristics at or beyond the absolute maximum ratings are not assumed or implied. All min and max voltage limits are referenced to ground.



Table 1. Absolute Maximum Ratings

Parameter	Min	Max	Units
Supply Voltage (VCC)		+3.3	V
Power Consumption		3.2	W
RF Input Voltage Swing (SE)		1.0	V
Case Temperature		+90	°C
Storage Temperature	-40	+100	°C
Operational Humidity	10	98	%
Storage Humidity	10	98	%

TERMINAL FUNCTIONS

TERMINAL			DESCRIPTION
Name	No.	Type	
High-Speed I/Os			
chip	5	CML input	Differential clock inputs with internal SE 50Ohm termination to VCC.
chin	6		
cop	15	CML output	Differential divided clock outputs with internal SE 50Ohm termination to VCC. Require external SE 50Ohm termination to VCC.
con	13		
Low-Speed I/Os			
reset	35	vee/vcc CMOS input	External active-high reset port
3wenin	36	1.2V CMOS input	3-wire enable active-low signal (SSn)
3wcin	38		3-wire input clock (SCLK)
3wdin	39		3-wire input data (MOSI)
3wdo	2	1.2V CMOS output	3-wire output data (MISO)
Digital Controls			
spion	3	vee/vcc CMOS input	External SPI activation port (active: high, SPI is enabled; default: low, SPI is disabled)
c0	19	vee/vcc CMOS input	Division binary control signals
c1	22		
c2	23		
c3	25		
c4	26		
c5	28		
c6	29		
c7	32		
Analog Controls			
iclk	8	Analog input	Power control ports with internal 800Ohm termination to vee; require external resistors between 120Ohm and 6KOhm connected to vee or external power supplies with current sinking capability; may be left not connected
icore	9		



Supply And Termination Voltages		
Name	Description	Pin Number
vcc	Main positive power supply or ground	4, 7, 12, 14, 16, 24, 27, 37
vdd	Digital positive power supply	18
vee	Negative power supply or ground	1, 10-11, 21, 30, 33, 40
nc	Not connected pins	17, 20, 31, 34

ELECTRICAL CHARACTERISTICS

PARAMETER	MIN	TYP	MAX	UNIT	COMMENTS
General Parameters					
vee		0.0		V	External ground
vcc	2.6	2.8	3.0	V	
vdd	1.2		1.3	V	very low current consumption
I _{vee}		920		mA	R=120Ω between iclk/icore and vee
		1250		mA	R>6KΩ between iclk/icore and vee
Power consumption		2.6		W	R=120Ω between iclk/icore and vee
		3.5		W	R>6KΩ between iclk/icore and vee
Junction temperature	-25	50	125	°C	
Input (chip/chin)					
Frequency	0.0		24	GHz	
Swing	75	400	1000	mV	Differential or SE, p-p; at 6GHz
CM Level	vcc- (SE swing)/2				
Rise/Fall Times			3	ns	20%-80%
Output (cop/con)					
Frequency	0.0		24	GHz	
Logic "1" level	vcc			V	
Logic "0" level	vcc-0.6			V	With external 50Ω DC termination
Rise/Fall Times	15	17	19	ps	20%-80%
Additive Jitter	TBD			ps	Peak-to-Peak
Duty Cycle	47%	50%	53%		For clock signal
Select (c0-c7) & Reset (reset)					
Logic "1" level	V _{CC} -0.4			V	
Logic "0" level	V _{EE} +0.4			V	

PACKAGE INFORMATION

The chip is packaged in a standard 40-pin QFN package shown Fig. 4. It is recommended that the center heat slug located on the back side of the package is soldered to ground to help dissipate heat generated by the chip during operation.

The part's identification label is ASNT8110A-PQB. The first 9 characters of the name before the dash identify the bare die including general circuit family, fabrication technology, specific circuit type, and part version while the 3 characters after the dash represent the package's manufacturer, type, and pin out count.



This device complies with the Restriction of Hazardous Substances (RoHS) per 2011/65/EU for all ten substances.

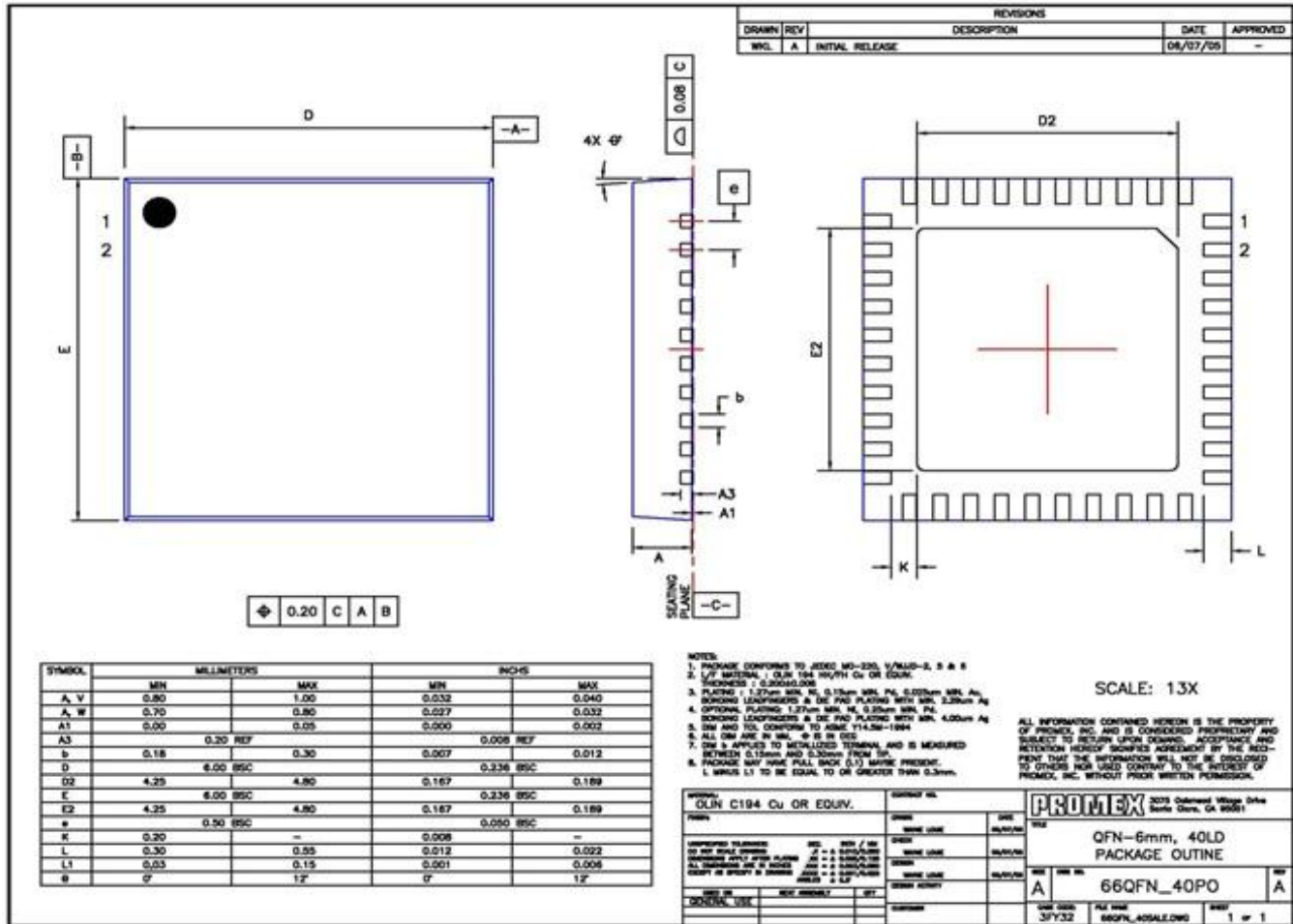


Fig. 4. QFN 40-Pin Package Drawing (All Dimensions in mm)

REVISION HISTORY

Revision	Date	Changes
1.3.2	02-2020	Updated Package Information
1.2.2	10-2019	Corrected input swing specifications
1.1.2	08-2019	Corrected header Corrected termination conditions for control ports Corrected minimum current/power consumption
1.0.1	07-2017	Corrected title Corrected maximum speed Corrected power consumption Corrected package drawing
0.0.1	04-2017	Preliminary release